KGF01 Series Data Sheet

Gyroscopes
Analog Output

KGF01-1001 — 75°/sec Single Axis X KGF01-1002 — 250°/sec Single Axis X



APPLICATIONS

Motion Detection

Inertial Navigation and Ded(uctive) Reckoning

Vehicle Stability Control
Vehicle Roll Detection
Adaptive Cruise Control
Platform Stabilization
Guidance Systems

FEATURES

PROPRIETARY TECHNOLOGY

High Sensitivity @ 40mV/(°/sec)

Broad Dynamic Range

Low Noise

Excellent Temperature Performance

Compact 24-pin SOIC Package

Self-test Function

User-Defined Low-pass Filter

Low Current Consumption

Kionix high performance silicon micromachined angular rate sensors consist of a sensor element and an ASIC packaged in a 24-pin SOIC open cavity package. The sensor element is fabricated from single-crystal silicon with proprietary Deep Reactive Ion Etching (DRIE) processes, and is protected from the environment by a hermetically-sealed silicon cap wafer at the wafer level.

The KGF01 series is designed to provide a high-signal-to-noise ratio with excellent performance over temperature. Sensitivity is factory programmable allowing customization for applications requiring $\pm 50^{\circ}/\text{sec}$ to 600°/sec ranges. Maximum sensor bandwidth is 75Hz. Lower settings are user-definable.

The sensor element functions on the principle of the Coriolis Effect and a capacitive-based sensing system. Rotation of the sensor causes a shift in response of an oscillating silicon structure resulting in a change in capacitance. An ASIC, using a standard CMOS manufacturing process, detects and transforms changes in capacitance into an analog output voltage, which is proportional to angular rate. The sensor element design utilizes differential capacitors and symmetry to significantly reduce errors from acceleration and off-axis rotations.



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KGF01 Series

PRODUCT SPECIFICATIONS

| PERFORMANCE SPECIFICATIONS | | | | | | |
|------------------------------------|-----------------------|-----------------------|------------|------------------------|--|--|
| PARAMETERS | UNITS | KGF01-1001 | KGF01-1002 | CONDITION | | |
| Range | °/sec | ±75 | ±250 | Factory Set | | |
| Sensitivity ¹ | mV/(°/sec) | 26.7 | 8.0 | Factory Set | | |
| Span | mV | ±2 | 000 | | | |
| Noise Density | °/sec/Hz ^½ | .(|)5 | | | |
| Noise | °/sec | .3 | 35 | DC50Hz | | |
| Bandwidth ² | Hz | 75 (default) or lower | | Hz @ 3dB | | |
| Operating Temp. | °C | -40 to 125 | | | | |
| Zero Rate Bias 3 | V | 2.500 ± 0.100 | | Room Temp | | |
| Temp. Drift of Zero Bias | °/sec | ± | 5.0 | Over chosen temp range | | |
| Temp. Drift of Sensitivity | % | ±3 | 3.0 | Over chosen temp range | | |
| Non-Linearity | % of FS | ±´ | 1.0 | | | |
| Non-ratiometric Error ³ | % | ±3 | 3.0 | | | |
| Cross-Axis Sensitivity | % of FS | ±2.0 | | Y Axis | | |
| | % 01 FS | ±1.0 | | Z Axis | | |
| | V | 5.0 ± 0.25 | | Voltage | | |
| Power Supply | V | -0.3 (min) 7.0 (max) | | Absolute min/max | | |
| | mA | 25mA (max) | | Current draw | | |

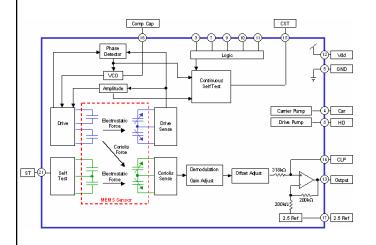
| ENVIRONMENTAL SPECIFICATIONS | | | | | | |
|-------------------------------|-------|-----------------------|-------|------------------|--|--|
| PARAMETERS | UNITS | KGF01-1001 KGF01-1002 | | CONDITION | | |
| Storage Temperature | °C | -55 t | o 150 | | | |
| Mechanical Shock ⁴ | g | 2000 | | Powered | | |
| Mechanical Shock | | 3000 | | Unpowered | | |
| ESD | V | 3000 | | Human body model | | |

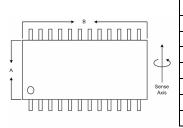
Notes

- 1 Custom sensitivities from 40mV/(°/sec) through 3.3mV/(°/sec) available.
- ² Bandwidth is factory programmed to 75Hz. A lower user-defined bandwidth adjustment is done with an external capacitor placed between CLP and GND.
- ³ Output is non-ratiometric. A non-ratiometric 2.5 VDC reference is provided at pin #17 as a scale reference for, e.g., A/D conversions.
- 4 Mechanical shock ratings based on survivability without permanent damage. Recovery time depends on characteristics of shock imparted to device.
- ⁵ The packaged device weighs .6 grams.

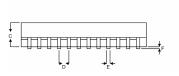
FUNCTIONAL DIAGRAM

24-PIN SOIC OPEN-CAVITY PACKAGE





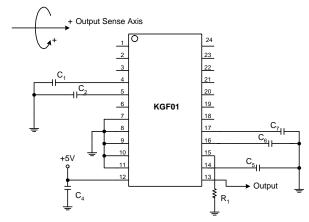
| Dimension | mones | WIIIIIIII CCC13 |
|-----------|-------------|-----------------|
| А | .308 / .301 | 7.83 / 7.64 |
| В | .614 / .599 | 15.60 / 15.20 |
| С | .128 / .108 | 3.25 / 2.74 |
| D | .060 / .040 | 1.52 / 1.02 |
| E | .020 / .013 | .51 / .33 |
| F | .011 / .004 | .27 / .10 |
| G | .419 / .394 | 10.64 / 10.01 |
| Н | .131 / .119 | 3.32 / 3.01 |





KGF01 Series

APPLICATION SCHEMATIC & PIN FUNCTION TABLE



| Pin | Function | Pin | Function |
|-----|------------|-----|-----------|
| 1 | DNC | 13 | Output |
| 2 | DNC | 14 | CLP |
| 3 | DNC | | CST |
| 4 | CAP Car | 16 | CompCap |
| 5 | CAP HD | 17 | 2.5 Ref |
| 6 | DNC | 18 | DNC |
| 7 | Reserved | 19 | V_T |
| 8 | GND | 20 | DNC |
| 9 | Reserved | 21 | Self Test |
| 10 | 0 Reserved | | DNC |
| 11 | Reserved | 23 | DNC |
| 12 | Vdd | 24 | DNC |

Definitions

2.5 Ref Fixed 2.5V reference. Allows scaling of sensor's non-ratiometric output. Tied to GND via C₇.

Cap CarRegulated ASIC reference voltage.Tied to GND via C1.Cap HDRegulated ASIC reference voltage.Tied to GND via C2.

CLP Single-pole low-pass filter capacitor; customer selectable. See note 3 below.

CompCap ASIC VCO control voltage. Tied to GND via C6.

CST Continuous self-test digital output. 5V when sensor operational; ground when fault. See note 4 below.

DNC Do not connect.

GND Ground.

Output Rate output with optional sensor fault indication.

Reserved For factory use; recommend grounding.

Self Test The output of a properly functioning part will increase by 50[d/s] (nom) when 5V is applied to the self-test pin #21.

Vdd Sensor supply voltage.

 V_{T} Temperature reference voltage for customer use. $V_{T} = 2.46 + (0.0016 * T[C])$ [VDC].

Notes

1. Recommend using 0.1μF for capacitors C₁, C₂, C₆, & C₇, 1.0 μF for decoupling capacitor C₄, and 100 k? for R₁.

2. External components must have same or greater operating temperature range as KGF01 sensor application. Recommended external component voltage and tolerance ratings are:

| Component | Min Voltage | Tolerance | Туре | |
|--|---|-----------|-------------|--|
| C ₁ , C ₂ | C ₁ , C ₂ 16 V C ₄ , C ₆ , C ₇ 10 V | | X7R or X5R* | |
| C ₄ , C ₆ , C ₇ | | | X7R or X5R* | |
| C ₅ | 10 V | ± 10% | X7R or X5R* | |
| R ₁ | 10 V | ± 5% | = 1/16 W | |

^{*} Type X7R operating temperature range -55°C - +125°C. Type X5R operating temperature range -25°C - +85°C.

- 3. C_5 implements a 1-pole filter cascaded upon an internal 75 Hz low-pass 3-pole Bessel filter. Even if the 75 Hz cutoff of the internal 3-pole filter is desired, C_5 should still be populated to reduce digital switching spikes on the output.
- 4. Resistor R_1 is recommended only if CST (pin #15) is monitored for fault indication in addition to fault indication provided by sensor output (pin #13) going to Vdd rail.
- 5. Since Kionix gyros are high-precision moving structures, please avoid ultrasonic operations such as ultrasonic cleansing.
- 6. An evaluation board is available upon request.

ORDERING GUIDE

| Product | Axis of Sensitivity | Range | Sensitivity (mV/g) | Offset (V) | Operating Voltage (V) | Temperature | Package |
|------------|------------------------|-------------|-----------------------|------------|--------------------------|----------------|-------------------------|
| KGF01-1001 | Х | 75 deg/sec | 26.7 | 2.5 | 5 | -40 to +125 °C | 24-pin SOIC Open Cavity |
| KGF01-1002 | X | 250 deg/sec | 8.0 | 2.5 | 5 | -40 to +125 °C | 24-pin SOIC Open Cavity |

