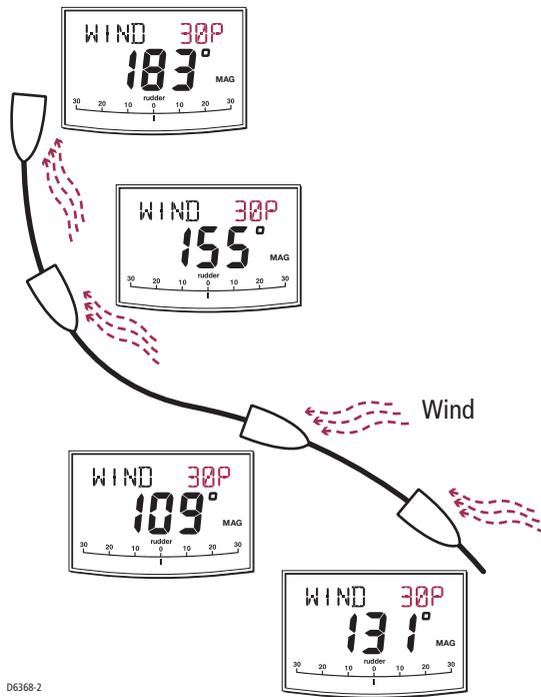## To Automatically Steer to a Fixed Wind Angle

auto **+** standby

WIND 455
128°
30 20 10 rudder 0 10 20

Wind

Wind

WIND 30P
183° MAG
30 20 10 rudder 0 10 20

WIND 30P
155° MAG
30 20 10 rudder 0 10 20

Wind

WIND 30P
109° MAG
30 20 10 rudder 0 10 20

WIND 30P
131° MAG
30 20 10 rudder 0 10 20

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Autotack

Auto Tack

WIND

= =

Auto Tack PORT

-1

+

-10

### Auto Tack STARBOARD

+1

+

+10
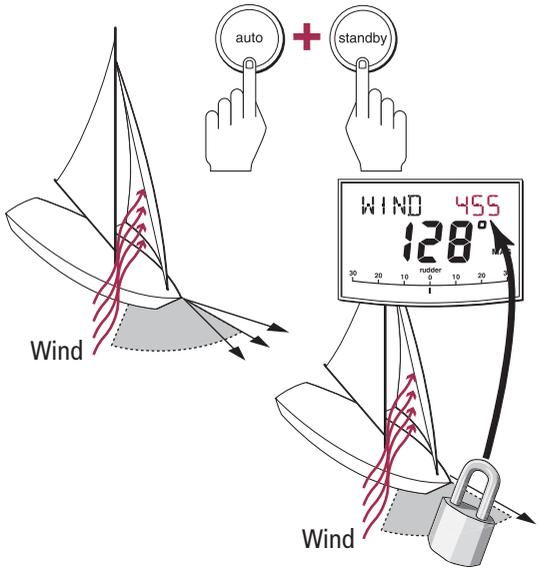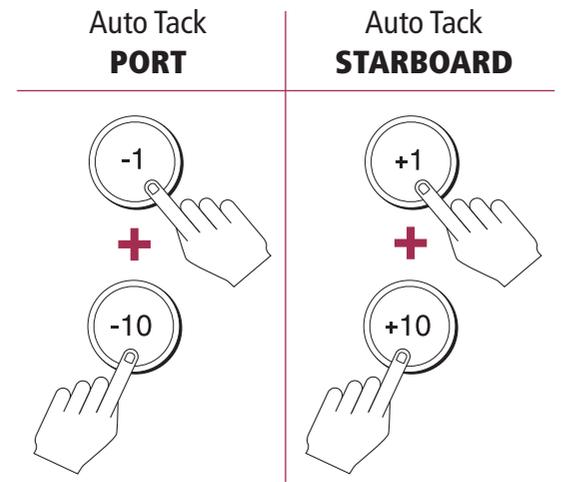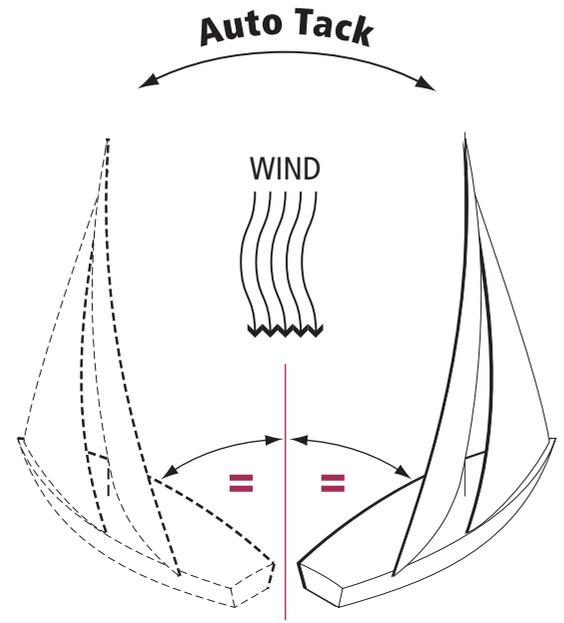
N.B. Refer to section 1.5 of the
ST6002 Operating Guide for full details

To Adjust Autopilot Course-keeping Accuracy

Autopilot response controls course keeping accuracy.
Higher response settings keep a tighter course but
increase the amount of drive activity and battery use.
Set to a level appropriate for your needs

-1 **+** +1

RESPONSE
3
30 20 10 rudder 0 10 20 30
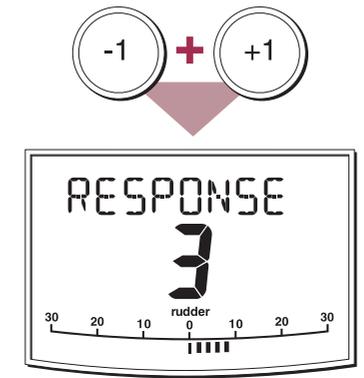
Use **-1** or **+1** to adjust response level.
Press **disp** to return to previous mode.

To Adjust Lighting Level

disp **1 sec**

LAMP
2
30 20 10 rudder 0 10 20 30
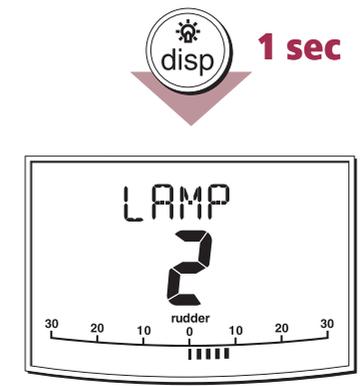
Use **disp** to adjust lighting level.
Wait 10 sec to return to previous mode.

86123-1

Raymarine®

SmartPilot®
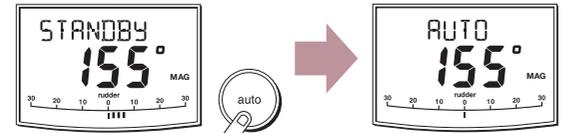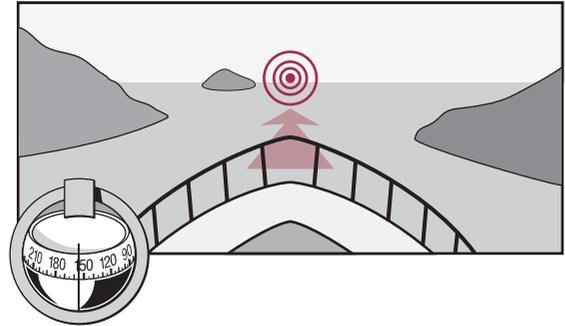### ST6002 Controller
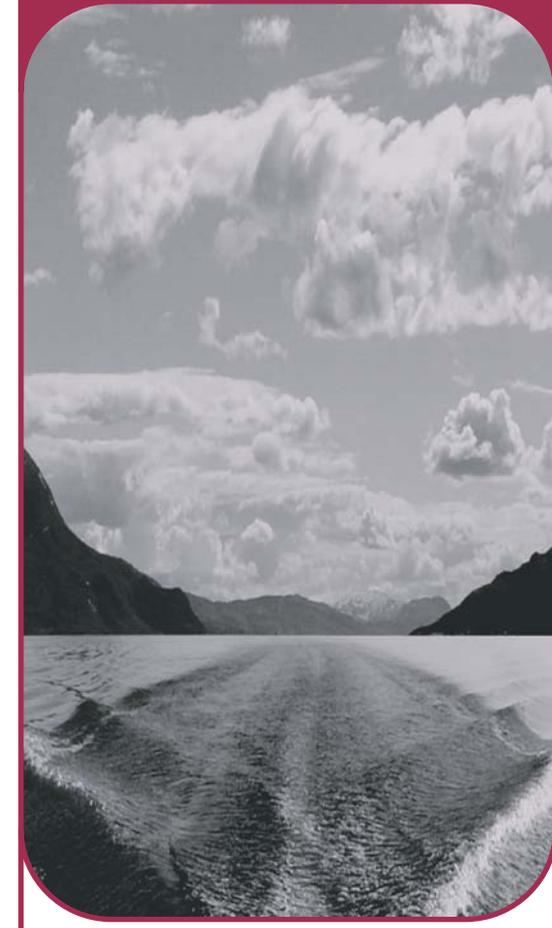
Quick Start Guide

Display Layout

standby
Press for Manual Control
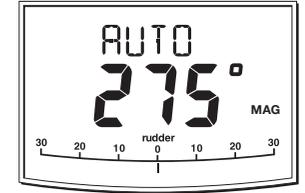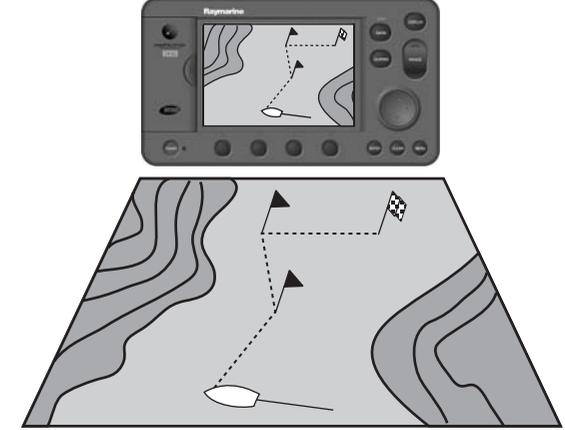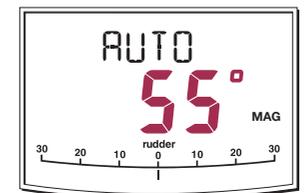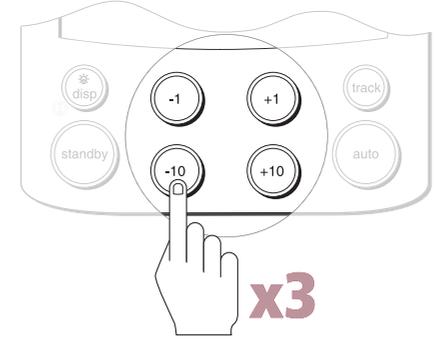
auto
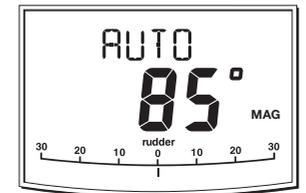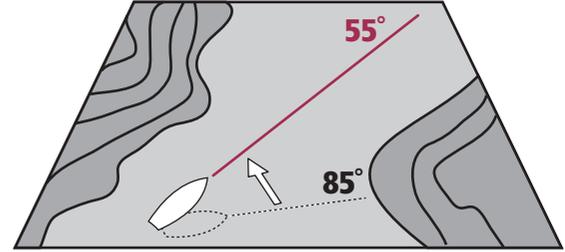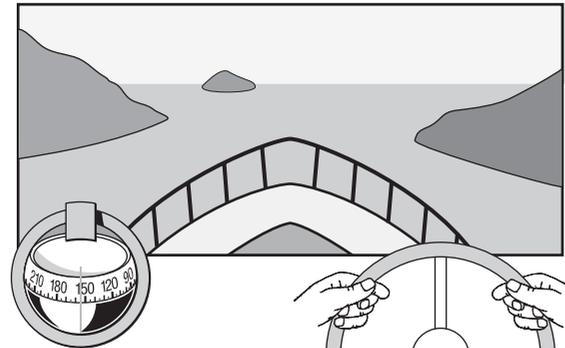Press to activate the Autopilot

course change keys
Port 1°   Starboard 1°
Port 10°   Starboard 10°

☀
disp
Press to display data pages

Press for 1 second for lamp control

Press for 3 seconds for power off

track
When the Autopilot is activated, press to follow a route from a connected navigation system.

Press again to accept the new course

To activate the Autopilot

STANDBY
155° MAG

auto ➡ AUTO
155° MAG

For Manual Control

AUTO
155° MAG

standby ➡ STANDBY
155° MAG

To change the Autopilot Heading

55°
85°

AUTO
85° MAG

-10   x3

AUTO
55° MAG

To follow a Route set on a Chartplotter

AUTO
275° MAG

track

STARBOARD
NEXT WPT
025° MAG

track   OK?

TRACK
025° MAG

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